

1 **Rhodium Oxide Nanorod Motors Powered by Light across the Full**
2 **Visible Spectrum**

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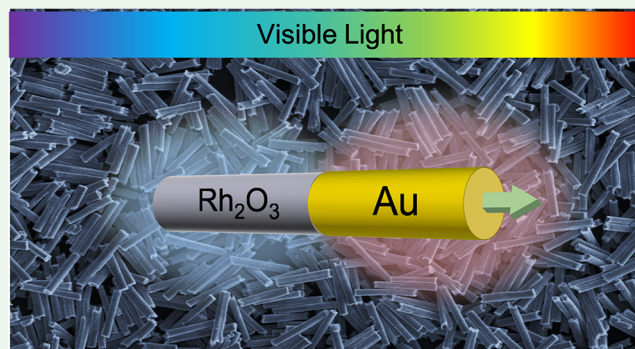
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Supporting Information

4 **ABSTRACT:** We report nanorod motors made of gold (Au) and
5 rhodium oxide (Rh_2O_3) that move in UV and visible light (purple,
6 blue, green, or red). These nanorods are synthesized in large
7 quantities (10^9 /batch) by template-assisted electrodeposition,
8 followed by annealing, and are uniformly distributed and resist
9 strong acids or bases. Rh_2O_3 forms a heterojunction with Au so
10 that a Rh_2O_3 -Au nanorod moves toward Au under visible light via
11 self-electrophoresis. Its speed increases with light intensities and
12 fuel [e.g., hydrogen peroxide (H_2O_2)] concentrations, reaching
13 $28.5 \mu\text{m/s}$ in 10% H_2O_2 under 365 nm light of 320 mW/cm^2 .
14 These nanorod motors also form dynamic and reversible clusters
15 under light.

16 **KEYWORDS:** *micro/nanomotor, electrodeposition, rhodium oxide, photocatalysis, large-scale synthesis*



17 **M**icro/nanomotors that convert energy stored in the
18 environment into motion at small scales have attracted
19 much attention in the past 20 years.^{1–3} Among the various
20 types of energy sources, light is particularly attractive because
21 of its tunability in intensity,^{4–11} polarization,¹² incident
22 direction,¹³ spatiotemporal distribution,¹⁴ and wave-
23 length,^{4,5,8,10,15–17} which allows for control of the speed and
24 direction of a nanomotor with high degrees of freedom.

25 The ability for a micro/nanomotor to respond to the entire
26 spectrum of visible light^{5–7,9–11} could open up even more
27 opportunities that not only enable new applications but also
28 facilitate the studies of active matter.¹⁸ Despite the recent
29 progress of micro/nanomotors that move under visible light,
30 such as BiVO_4 ,¹⁹ $\text{Cu}_2\text{O-Au}$,¹⁷ $\text{Fe}_2\text{O}_3\text{-Au}$,¹⁶ C_3N_4 ,¹⁵ B-TiO_2 ,⁴
31 etc., only a few can move in the entire spectrum of visible light
32 (400–700 nm). Examples include dye-sensitized nanotree
33 swimmers,¹⁰ $\text{Zn}_x\text{Cd}_{1-x}\text{Se}$ alloy nanowire motors,⁷ and bubble-
34 propelled tubular micromotors functionalized with quantum
35 dots.⁹ There is a continuous need for the development of new
36 light-driven micro/nanomotors that move under the full
37 spectrum of visible light, preferably in large quantities to
38 reduce cost and enable studies of their collective behaviors.^{20,21}

39 Here, we report nanorods made of rhodium oxide (Rh_2O_3)
40 and gold (Au) that autonomously move toward the Au side in
41 aqueous solutions of hydrogen peroxide (H_2O_2) under
42 illumination of light from UV through the full visible spectrum.
43 Its speed can be easily tuned by adjusting the H_2O_2
44 concentration, the intensity, or the wavelength of incident
45 light. These Rh_2O_3 -Au nanorods can be synthesized uniformly
46 in large quantities (10^9 /batch) by template-assisted electro-
47 chemical deposition, making it a good model system for

studying their collective behaviors.^{22,23} As an example, we
48 showcase at the end the reversible assembly of a dense
49 population of these rods into dynamic clusters. These Au-
50 Rh_2O_3 motors swim at ~ 1 body length/s in 0.1% H_2O_2 under
51 80 mW/cm^2 and are therefore potentially useful for environ-
52 mental sensing and remediation under sunlight.

53 Rh_2O_3 -Au nanorods were prepared by annealing Rh-Au
54 nanorods in air (shown in Figure 1a). First, Rh-Au bimetallic
55 nanorods of $\sim 310 \text{ nm}$ diameter and $\sim 2.6 \mu\text{m}$ length were first
56 electrodeposited in a commercially available aluminum oxide
57 (AAO) template. Then, the nanorod-filled template was
58 annealed in an air-filled furnace to oxidize Rh into Rh_2O_3 ,
59 typically at $700 \text{ }^\circ\text{C}$ for 4 h (this is the optimum annealing
60 condition chosen from a range of conditions listed in Table
61 S1). The AAO template was then dissolved in sodium
62 hydroxide (NaOH), yielding roughly 2 billion (2×10^9)
63 Rh_2O_3 -Au nanorods from one commercial AAO membrane of
64 25 mm diameter. More experimental details are given in the
65 Supporting Information (SI).

66 Representative images of these rods under a scanning
67 electron microscope are given in Figure 1b. These samples
68 were highly uniform in size, with the polydispersity index
69 (PDI) being ~ 0.01 for rod diameters of $307 \pm 34 \text{ nm}$ and 70

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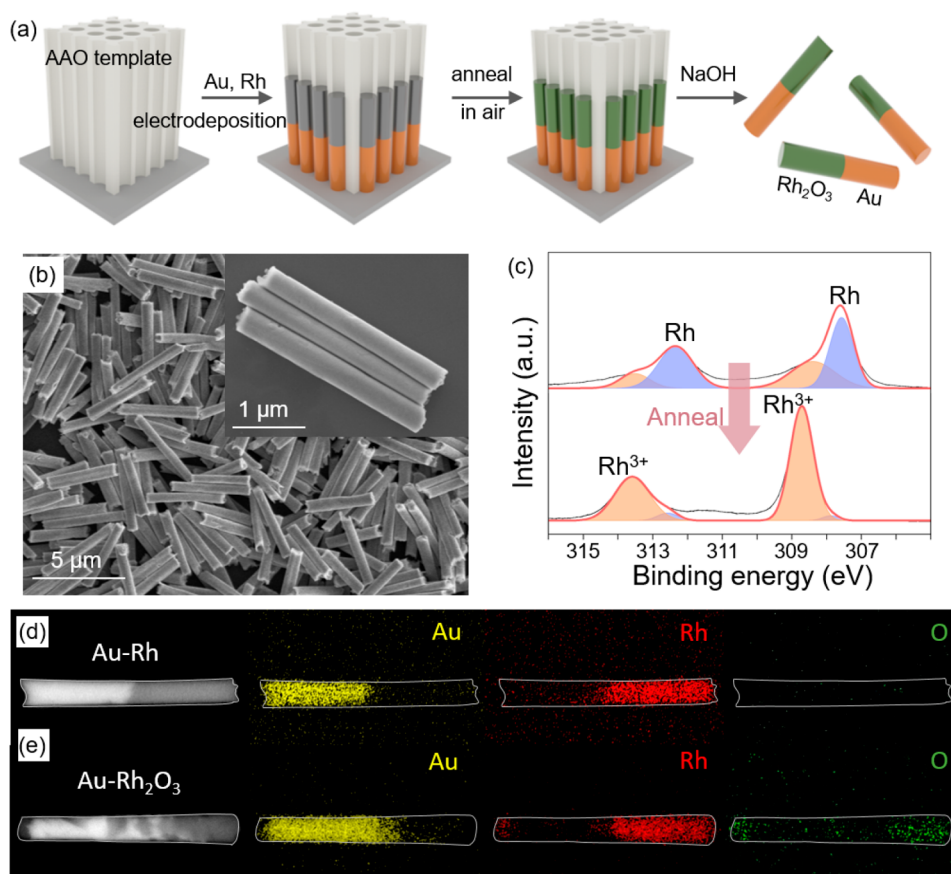


Figure 1. Preparation and characterization of Rh_2O_3 -Au nanorod motors. (a) Synthesis of Rh_2O_3 -Au nanorods by electrodeposition in an AAO template, followed by annealing in a furnace. See the main text and S1 for details. (b) SEM images of Rh_2O_3 -Au rods. (c) XPS spectra suggesting conversion from Rh^0 to Rh^{3+} on the rod surface after annealing. (d and e) Backscattered SEM images and elemental mapping of Au, Rh, and O for a Rh-Au rod (d) and a Rh_2O_3 -Au rod (e).

71 ~ 0.02 for rod lengths of $2.59 \pm 0.32 \mu\text{m}$ (see Figure S1 for size
72 distributions; PDI is defined as the square of the standard
73 deviation divided by the mean value²⁴). The small but
74 nonnegligible sample polydispersity was caused either by the
75 intrinsic nonuniformity of the membrane or by the electro-
76 deposition process. X-ray photoelectron spectroscopy (XPS;
77 Figure 1c) and scanning electron microscopy–elemental
78 mapping (SEM–EDS; Figure 1d,e) confirmed the successful
79 conversion of Rh to Rh_2O_3 after annealing and that Rh_2O_3 and
80 Au were mainly located at either end of the bisegmented rod. A
81 similar conversion from Rh to Rh_2O_3 by thermal annealing was
82 reported in ref 25 although not for nanorods.

83 A few comments are worth noting regarding the synthesis of
84 a Rh_2O_3 -Au nanorod. First, nanorods of different lengths can
85 be made by varying the deposition conditions, and nanorods of
86 metal segments other than Au can be synthesized by replacing
87 the plating solutions. Second, Au and Rh tend to diffuse into
88 each other during annealing (see Figure 1e for an example).
89 Such a diffusion could lead to rods of more erratic distributions
90 of Au and Rh_2O_3 and could contribute to the circular motion
91 of the Rh_2O_3 -Au nanomotors in H_2O_2 . A complete under-
92 standing of how the material diffusion affects the resulting
93 motion is, however, lacking at the moment. Finally, annealing
94 at high temperatures and for long duration often causes severe
95 deformation of the rods (see Figure S1 for an example), while
96 annealing at low temperatures and for shorter duration might
97 not fully oxidize the rods. The latter issue could, in principle,

be resolved by increasing the partial pressure of oxygen based
98 on simple thermodynamic reasoning. A wide range of synthesis
99 conditions have been tested, and the results are listed in Table
100 S1.
101

Rh_2O_3 -Au rods moved toward the Au end in a H_2O_2
102 solution when illuminated by light but only showed Brownian
103 motion without light (Figure 2a). As a result, their propulsion
104 can be switched on or off with light (Figure 2b). They often
105 moved in spiral or circular trajectories, possibly because of the
106 diffusion of metal segments during annealing described above
107 or the intrinsic shape asymmetry of rods from the
108 nonuniformity of the template. Most notably, Rh_2O_3 -Au
109 nanorods were able to move in light across the full visible
110 spectrum, but they moved more slowly as the wavelength
111 shifted to red. Examples of their propulsion in purple, blue,
112 green, and red light are shown in Figure 2c–f (note that they
113 moved even faster in UV light, but this result is expected and
114 therefore not shown here; moreover, red light beyond 660 nm
115 was not tested in order to minimize the photothermal effect of
116 Au, which could complicate a rod's propulsion). In addition,
117 they moved faster in higher concentrations of H_2O_2 and higher
118 light intensity (Figure 2g,h), consistent with typical photo-
119 catalytic micro/nanomotors reported in the literature.^{4,9,16,17}
120 As a result, their speeds can be precisely tuned by a
121 combination of these experimental parameters. As a special
122 case, these Au- Rh_2O_3 motors swim at $2.2 \mu\text{m/s}$ in 0.1% H_2O_2
123 under 80 mW/cm^2 , a reasonable condition for processing
124

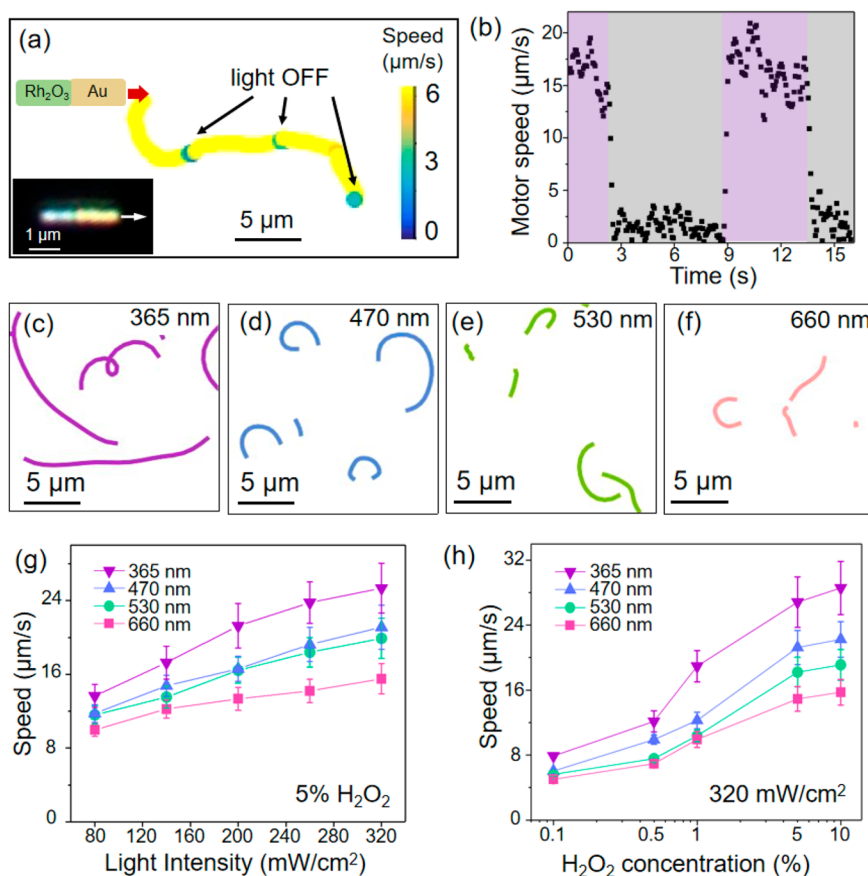


Figure 2. Motion of Rh_2O_3 -Au nanorod motors. (a) Trajectory of a Rh_2O_3 -Au nanorod over 6 s in 5% H_2O_2 under 470 nm light (taken from Video S1). Light was turned off at three labeled instances. The trajectory is color-coded with the instantaneous speed of the motor. Inset: Rh_2O_3 -Au nanorod moving toward the Au end, as seen under dark-field microscopy (taken from Video S2). (b) Instantaneous speeds of a Rh_2O_3 -Au nanorod when 470 nm light was switched on and off. (c-f) Trajectory of Rh_2O_3 -Au nanorods over 2 s in 5% H_2O_2 under light of 365, 470, 530, and 660 nm, respectively (taken from Video S3). Average speeds of Rh_2O_3 -Au nanomotors under different wavelengths of light (g) and in different concentrations of H_2O_2 (h). The error bars in parts g and h are standard deviations of ~ 50 measurements. The data in parts g and h are from Video S4.

125 wastewater under sun light, suggesting potential applications in
126 environmental remediation.

127 We propose that a Rh_2O_3 -Au nanorod contains a
128 heterojunction that enables photocatalysis, which moves the
129 rod via self-electrophoresis. To elaborate, Rh_2O_3 is a p-type
130 semiconductor with a band gap of ~ 1.41 eV,²⁶ corresponding
131 to a maximum absorption wavelength of up to ~ 880 nm.
132 Rh_2O_3 then forms a Schottky junction with Au so that, when
133 illuminated by light, electrons and holes are excited in Rh_2O_3
134 and preferably transported to the Rh_2O_3 -water and Au-water
135 interfaces, respectively, where the reduction and oxidation half-
136 reaction of H_2O_2 occurs (see Figure 3a for the schematic). As a
137 result, a proton gradient is generated around the nanorod
138 pointing from the Au end to the Rh_2O_3 end, and the negatively
139 charged nanorod (ζ potential of -46 mV) moves in this self-
140 generated electric field and toward Au. This mechanism,
141 known as self-electrophoresis,²⁷ is widely believed to be
142 responsible for the autonomous motion of the classic
143 bimetallic nanorods in H_2O_2 ,²⁸ as well as many other
144 photocatalytic nanomotors consisting of a metal-semiconduc-
145 tor heterojunction.^{4,6,8,16,17,20}

146 Self-electrophoresis of a Rh_2O_3 -Au nanorod undergoing
147 photocatalysis is supported by photocurrent measurements.
148 First, as shown in Figure 3b,c, photogenerated electrons flow
149 from a Au electrode to a Rh_2O_3 electrode immersed in aqueous

H_2O_2 solutions when illuminated by light. The presence of
such a photocurrent between Rh_2O_3 and Au and its direction
are consistent with the proposed mechanism. Second, parts d-
g of Figure 3 show that the changes in the photocurrents
match those in the motor speeds when the light intensities and
wavelengths were varied. This provides strong evidence that
the motor speeds are directly related to the photocurrents,
which dictate the ion fluxes in and out of a Rh_2O_3 -Au
nanorod and ultimately the strength of the self-generated
electric field.

One advantage of Rh_2O_3 -Au nanomotors synthesized by
electrodeposition is their large quantities, which enables the
study of collective behaviors in population densities (φ ,
defined as 2D coverage) as high as 75%. Experiments of such
high population densities are difficult for other photocatalytic
nanomotors, such as those made of silicon nanowires¹¹ or by
asymmetrically coating TiO_2 microspheres,²⁰ mostly because
of the limited amount of sample. No significant bubble was
observed even at very concentrated suspensions possibly
because Rh_2O_3 is not as catalytically active toward the
decomposition of H_2O_2 as Rh is. This lack of large bubbles
is yet another key advantage over conventional bimetallic
nanorod motors because it permits experiments of large
population densities, as we demonstrated in this paper.

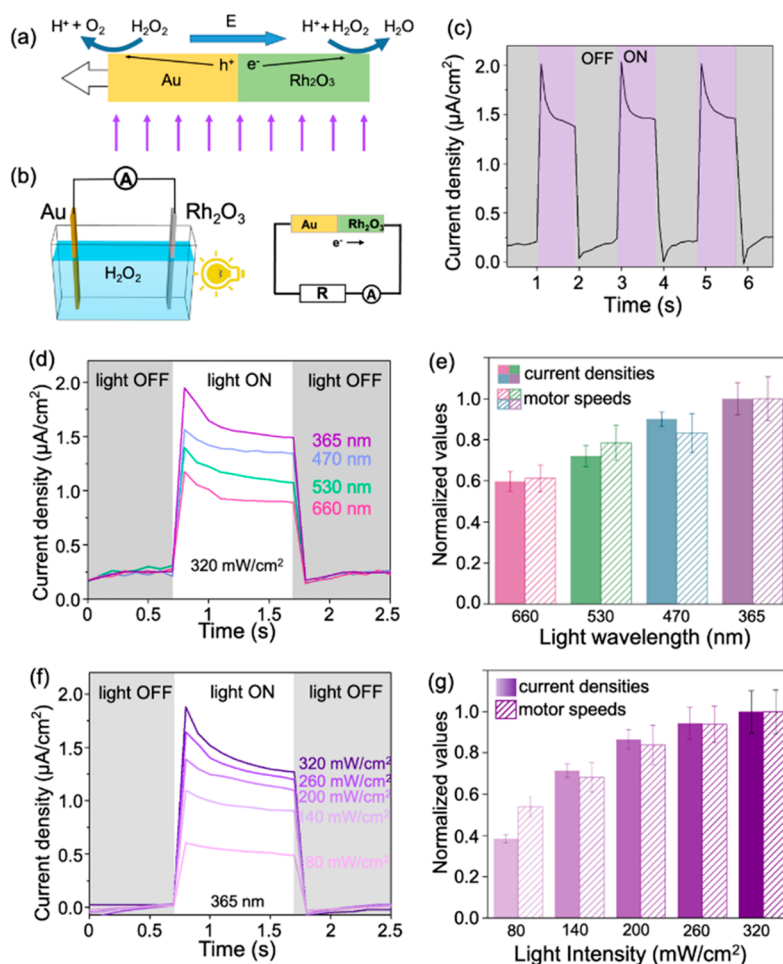


Figure 3. Propulsion mechanism of Rh₂O₃-Au nanomotors. (a) Schematic of self-electrophoresis of a Rh₂O₃-Au nanorod in H₂O₂. See the main text for detailed descriptions. (b) Schematic of the electrochemical setup to measure the photocurrent between Au and Rh₂O₃ electrodes and an equivalent circuit. Positive photocurrent values correspond to electrons flowing from Au to Rh₂O₃. (c) Instantaneous photocurrents measured with the setup shown as part b in 5% H₂O₂ under 365 nm light of 320 mW/cm². (d) Photocurrent densities in 5% H₂O₂ under light of different wavelengths, with the same light intensity of 320 mW/cm². These results are normalized and compared in part e with motor speeds obtained under the same lighting conditions (speed data obtained from Figure 2g). (f and g) Photocurrent densities and motor speeds at different light intensities in 5% H₂O₂ under 365 nm light. The error bars of the current densities in parts e and g are standard deviations of photocurrent measurements during the entire period of illumination in parts d and f, respectively. The error bars of the motor speeds are from Figure 2g.

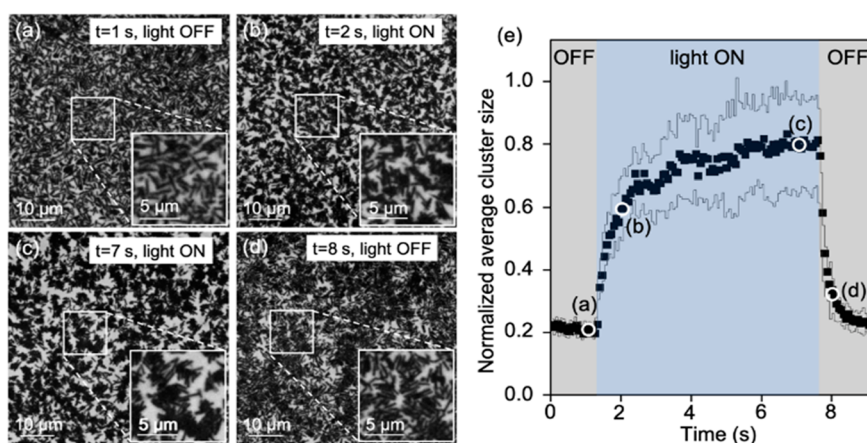


Figure 4. Dynamic clustering of Rh₂O₃-Au motors (snapshots taken from Video S5). (a) Rh₂O₃-Au rods of a 2D coverage $\phi = 67\%$ were suspended in 5% H₂O₂. (b) Rods quickly formed moving clusters when irradiated with 470 nm light of 200 mW/cm². (c) Over a few seconds, clusters of Rh₂O₃-Au rods reached a steady-state size distribution. (d) Clusters disintegrated when light was switched off. (e) Normalized cluster size (defined as the number of rods in a cluster) measured over time, with the labeled time instances corresponding to parts a-d. The error bars are the standard deviations of all of the cluster sizes measured in one optical micrograph.

174 As an example of the collective behaviors of Rh₂O₃-Au
175 nanorods under light, Figure 4 and Video S5 show that
176 Rh₂O₃-Au nanorods of $\varphi = 67\%$ quickly formed dynamic
177 clusters in 5% H₂O₂ when irradiated by blue light (470 nm) for
178 a few seconds. These dynamic clusters formed and broke
179 continuously, and each cluster could rotate or move linearly
180 depending on the exact arrangement of the rods within a
181 cluster. Clusters dissolved when light was switched off. This
182 dynamic process is quantified in Figure 4e by the rise and fall
183 of the average cluster size. Experiments performed in other
184 concentrations of H₂O₂ or light intensities/wavelengths were
185 not qualitatively different from the example shown here, as
186 long as rods were motile.

187 Finally, we note that another key advantage of Rh₂O₃-Au
188 nanorods over nanorod motors made of Cu₂O¹⁷ or iron
189 oxides¹⁶ is their chemical inertness toward strong acids or
190 bases. For example, Figure S3 confirms that Rh₂O₃-Au
191 nanorods remained structurally intact after soaking in 68%
192 HNO₃ or 10 mol/L NaOH solutions overnight and were still
193 motile in H₂O₂ afterward. Although acid/base resistant,
194 Rh₂O₃-Au nanorods cannot move in strong acids or bases
195 because self-electrophoresis fails at high ionic strengths, a well-
196 known limitation to this particular driving mechanism.²⁹

197 In conclusion, we have developed Rh₂O₃-Au nanorod
198 motors that autonomously move in the full spectrum of visible
199 light in H₂O₂ aqueous solution via self-electrophoresis. They
200 are synthesized uniformly in large scale using template-assisted
201 electrochemical deposition. Their speeds can be easily and
202 precisely controlled by varying the fuel concentration, light
203 intensity, and wavelength. A maximum speed of 28.5 $\mu\text{m/s}$ was
204 found in 10% H₂O₂ irradiated with 365 nm light of 320 mW/
205 cm². Rh₂O₃-Au nanorod motors readily form dynamic,
206 reversible clusters, at population densities as high as 67%.
207 Rh₂O₃-Au nanorod motors reported here could be used for
208 environmental remediation, microassembly, or cargo delivery
209 under visible light. They are also a good model system for
210 studying rod-shaped active matter,^{22,30} particularly at high
211 population densities.

212 ■ ASSOCIATED CONTENT

213 **SI** Supporting Information

214 The Supporting Information is available free of charge at
215 <https://pubs.acs.org/doi/10.1021/acsanm.2c03560>.

216 Synthesis of micromotors, supporting data including the
217 preparation details, size distribution, annealing condi-
218 tion, and inertness against strong acid and base, the
219 motor experiment, and electrochemical measurements
220 (PDF)

221 Au-Rh₂O₃ nanomotors activated or stopped by switch-
222 ing the lamp on and off (motors in 5% H₂O₂ under 470
223 nm light of 200 mW/cm²) (MP4)

224 Observing the moving direction of Au-Rh₂O₃ nano-
225 motors in the dark field [3 \times speed; motor in 5% H₂O₂
226 under a mercury lamp of ~ 50 mW/cm²; this video was
227 taken with an upright microscope (Olympus BX51M) in
228 the reflective mode] (MP4)

229 Au-Rh₂O₃ nanomotors moving under the illumination
230 of different wavelengths (motors in 5% H₂O₂ under 365,
231 470, 530, and 660 nm light of 200 mW/cm²) (MP4)

232 Au-Rh₂O₃ nanomotors moving under different illumi-
233 nation intensities and in different concentrations of

H₂O₂ (motors under 365, 470, 530, and 660 nm light) 234
(MP4) 235

Collective behaviors of Au-Rh₂O₃ nanomotors (motors 236
in 5% H₂O₂ under 470 nm light of 200 mW/cm²) 237
(MP4) 238

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260 Notes

261 The authors declare no competing financial interest.

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